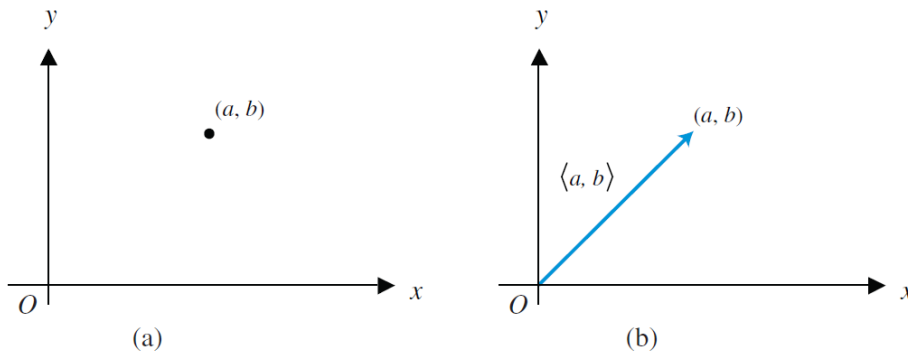


## 6.1 VECTORS IN THE PLANE

Objectives: Apply the arithmetic of vectors; Use vectors to solve real-world problems

### Two-Dimension Vectors

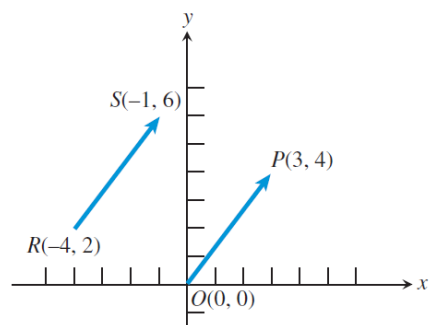
- A \_\_\_\_\_ is an ordered pair of real numbers, denoted in \_\_\_\_\_ as  $\langle a, b \rangle$ .
  - The numbers  $a$  and  $b$  are the \_\_\_\_\_ of the vector  $v$
  - The \_\_\_\_\_ of the vector  $\langle a, b \rangle$  is the arrow from the origin to the point  $(a, b)$
  - The \_\_\_\_\_ of  $v$  is the length of the vector and the \_\_\_\_\_ of  $v$  is the direction in which the arrow is pointing



**FIGURE 6.1** The point represents the ordered pair  $(a, b)$ . The arrow (directed line segment) represents the vector  $\langle a, b \rangle$ .

- The vector  $0 = \langle 0, 0 \rangle$ , called the \_\_\_\_\_, has zero length and no direction
- Any two arrows with the same length and pointing in the same direction represent the same vector

- The arrows  $\overrightarrow{RS}$  &  $\overrightarrow{OP}$  both represent the vector  $\langle 3, 4 \rangle$ , as would any arrow with the same length pointing in the same direction.
  - Such arrows are called \_\_\_\_\_



- Head Minus Tail (HMT) Rule
  - If an arrow has initial point  $(x_1, y_1)$  and terminal point  $(x_2, y_2)$ , it represents the vector \_\_\_\_\_

➤ Magnitude

- The magnitude of a vector  $v$  is also called the \_\_\_\_\_ of  $v$ ,  $|v|$  or  $\|v\|$
- If  $v$  is represented by the arrow from  $(x_1, y_1)$  to  $(x_2, y_2)$ , then \_\_\_\_\_
  - If  $v = \langle a, b \rangle$ , then  $|v| =$  \_\_\_\_\_

**Example 1: Showing Arrows are Equivalent**

Prove that  $\overrightarrow{RS}$  and  $\overrightarrow{PQ}$  are equivalent by showing that they represent the same vector:  $R = (-4, 2)$ ,  $S = (-1, 6)$ ,  $P = (2, -1)$ , &  $Q = (5, 3)$

**Example 2: Finding Magnitude of a Vector**

Find the magnitude of the vector  $v$  represented by  $\overrightarrow{PQ}$ , where  $P = (-3, 4)$  &  $Q = (-5, 2)$ .

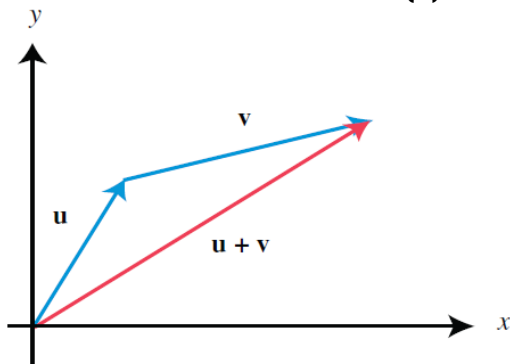
🌀 Vector Operations

➤ Vector Addition

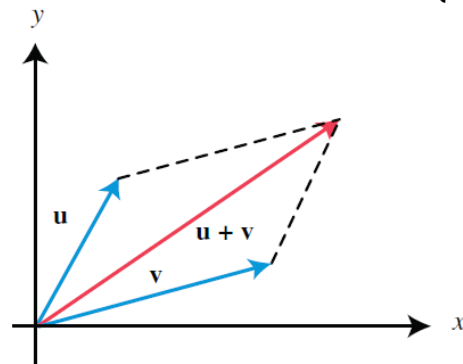
- Let  $u = \langle u_1, u_2 \rangle$  and  $v = \langle v_1, v_2 \rangle$  be vectors and let  $k$  be a real number (scalar). The sum (or resultant) of the vectors  $u$  &  $v$  is the vector... \_\_\_\_\_
- The product of the scalar  $k$  and the vector  $u$  is... \_\_\_\_\_

➤ The sum of the vectors  $u$  &  $v$  can be represented geometrically by arrows in two ways.

- Tail-to-head representation (a)
- Parallelogram representation (b)



(a)



(b)

### Example 3: Performing Vector Operations

Let  $u = \langle 2, -1 \rangle$ ,  $v = \langle 1, 3 \rangle$ , &  $w = \langle -1, -1 \rangle$ . Find the component form of the following vectors:

(a)  $-u + v$

(b)  $u + (-1)w$

(c)  $-u + w$

(d)  $3u + 2v$

(e)  $-v - 2w$

### Unit Vectors

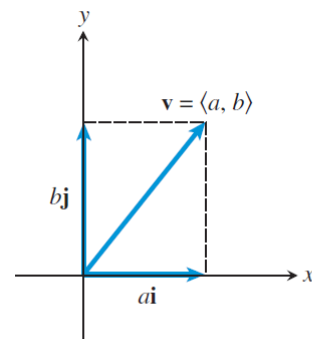
- A vector  $u$  with length  $|u| = 1$  is a unit vector.
  - If  $v$  is not the zero vector  $\langle 0, 0 \rangle$ , then the vector

...is a unit vector in the direction of  $v$ .

### Standard Unit Vectors

- Any vector  $v$  can be written as an expression in terms of the standard unit vector:

- $v = \langle a, b \rangle$  is expressed as the \_\_\_\_\_  
\_\_\_\_\_  $ai + bj$  of the vectors  
i & j
- The scalars  $a$  &  $b$  are the \_\_\_\_\_  
and \_\_\_\_\_ of the vector  $v$



### Example 4: Finding a Unit Vector

Find the unit vector in the direction of the given vector.

(a)  $u = \langle 2, -1 \rangle$

(b)  $v = 3i + 2j$

**FIGURE 6.9** The vector  $v$  is equal to  $ai + bj$ .

## 🌀 Direction Angles

- A simple but precise way to specify the direction of a vector  $v$  is to state its direction angle, the angle  $\theta$  that \_\_\_\_\_
- Resolving the Vector
  - If  $v$  has direction angle  $\theta$ , the components of  $v$  can be expressed using the formula...  
\_\_\_\_\_

### Example 5: Finding the Components of a Vector

Find the components of a given vector.

(a)  $u$  with direction angle  $105^\circ$  and magnitude 8

(b)  $v$  with direction angle  $75^\circ$  and magnitude 7.5

### Example 6: Finding the Direction Angle of a Vector

Find the magnitude and direction of each vector.

(a)  $u = \langle 1, 4 \rangle$

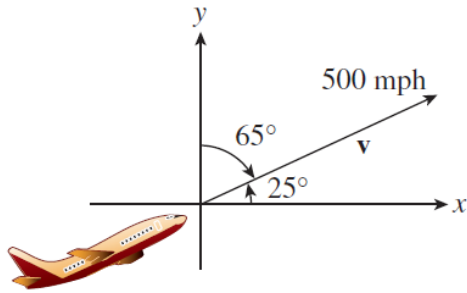
(b)  $v = \langle -5, 4 \rangle$

(c)  $w = \langle 3, -2 \rangle$

## 🌀 Applications of Vectors

- The \_\_\_\_\_ of a moving object is a vector because velocity has both magnitude and direction.
  - The magnitude of velocity is **speed**.

**Example 9: Writing Velocity as a Vector**



A DC-10 jet aircraft is flying on a bearing of  $65^\circ$  at 500 mph. Find the component form of the velocity of the airplane. Recall that the bearing is the angle that the line of travel makes with due north, measured clockwise.



**6.2 DOT PRODUCT OF VECTORS**

Objectives: Calculate the dot product of vectors

**∞** The Dot Product

➤ The dot product or inner product of  $u = \langle u_1, u_2 \rangle$  &  $v = \langle v_1, v_2 \rangle$  is...

**Examples: Finding Dot Products**

Find the dot product of the given vectors.

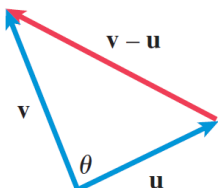
1.  $u = \langle 3, 1 \rangle$  &  $v = \langle 2, -5 \rangle$
2.  $u = \langle 5, 4 \rangle$  &  $v = \langle -4, 5 \rangle$
3.  $u = (-2i + 2j)$  &  $v = (3i - 5j)$

**Example 4: Using Dot Product to Find Length**

Use the dot product to find the length of the vector  $u = \langle 4, -3 \rangle$

**∞** Angle Between Vectors

➤ If  $\theta$  is the angle between the nonzero vectors  $u$  &  $v$ , then...



$\cos \theta =$  \_\_\_\_\_

**FIGURE 6.16** The angle  $\theta$  between nonzero vectors  $u$  and  $v$ .

### Examples: Finding the Angle between Vectors

Find the angle between the two given vectors.

5.  $u = \langle 4, 3 \rangle$  &  $v = \langle -3, -1 \rangle$

6.  $u = \langle 5, 3 \rangle$  &  $v = \langle -1, -3 \rangle$

7.  $u = i + \sqrt{2}j$  &  $v = -\sqrt{2}i - 4j$

### Orthogonal Vectors

- The vectors  $u$  and  $v$  are orthogonal if and only if \_\_\_\_\_
  - The terms “perpendicular” and “orthogonal” almost mean the same thing

#### Example 8: Proving Vectors are Orthogonal

Prove that the vectors  $u = \langle 2, 3 \rangle$  &  $v = \langle -6, 4 \rangle$  are orthogonal by showing that their dot product is zero.

#### Example 8: Parallel, Orthogonal or Neither?

Determine whether the vectors  $u = \langle 2, -7 \rangle$  &  $v = \langle -4, 14 \rangle$  are parallel, orthogonal, or neither.

## 6.3 PARAMETRIC EQUATIONS

Objectives: Define parametric equations, eliminate the parameter, and find parametric equations for a line

### Parametric Equations & Curves

- The graph of the ordered pairs  $(x, y)$  where  $x = f(t)$  &  $y = g(t)$  are functions defined on an interval  $I$  of  $t$ -values is a \_\_\_\_\_. The equations are called \_\_\_\_\_ for the curve, the variable  $t$  is a \_\_\_\_\_.

### Eliminating the Parameter

- When a curve is defined parametrically it is sometimes possible to \_\_\_\_\_ and obtain a rectangular equation in  $x$  &  $y$  that represents the curve.

#### Examples: Eliminating the Parameter

Eliminate the parameter and identify the graph of the parametric curve – a line, parabola, or a circle.

1.  $x = 2 - t, y = 2t + 1$

2.  $x = t^2, y = 2 - t$

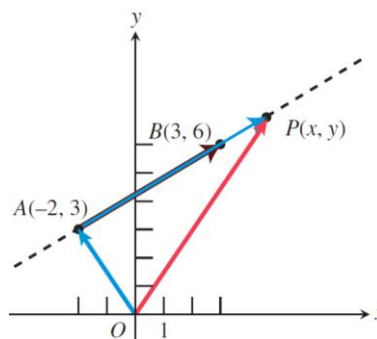
3.  $x = t - 2, y = 1 + 2t^2$

4.  $x = 6 \cos t, y = 6 \sin t, 0 \leq t \leq 2\pi$

## Lines and Line Segments

➤ We can use vectors to help us find parametric equations for a line.

- Example: Find a parametrization of the line through the points  $A(-2, 3)$  &  $B(3, 6)$ 
  - Let  $P(x, y)$  be an arbitrary point on the line through  $A$  &  $B$ .



- The vector  $\vec{OP}$  is the tail-to-head vector sum of  $\vec{OA}$  &  $\vec{AP}$  and  $\vec{AP}$  is a scalar multiple of  $\vec{AB}$ .

$$\vec{OP} = \vec{OA} + \vec{AP}$$

$$\vec{OP} = \vec{OA} + t \cdot \vec{AB}$$

$$\langle x, y \rangle = \langle -2, 3 \rangle + t \langle 3 - (-2), 6 - 3 \rangle$$

$$\langle x, y \rangle = \langle -2, 3 \rangle + t \langle 5, 3 \rangle$$

$$\langle x, y \rangle = \langle -2 + 5t, 3 + 3t \rangle$$

### Examples: Finding Parametric Equations for a Line Segment

Find the parametrization of the line segment with endpoints  $A$  &  $B$ .

5.  $A = (1, -1), B = (-2, 7)$

6.  $A = (12, -2), B = (4, 3)$



## 6.4 POLAR COORDINATES

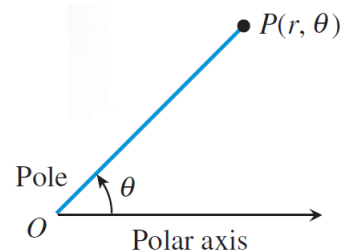
Objectives: Convert points and equations from polar to rectangular coordinates and vice versa

### 🌀 Polar Coordinate System

➤ A \_\_\_\_\_ is a plane with a point  $O$ , the \_\_\_\_\_, and a ray from  $O$  to the \_\_\_\_\_

➤ Each point  $P$  in the plane is assigned as \_\_\_\_\_ follows:

- $r$  is the \_\_\_\_\_ from  $O$  to  $P$
- $\theta$  is the \_\_\_\_\_ whose initial side is on the polar axis and whose terminal side is on the line  $OP$ 
  - As in trigonometry, we measure  $\theta$  as positive when moving counterclockwise; negative when moving clockwise
  - If  $r > 0$ , then  $P$  is on the terminal side of  $\theta$
  - If  $r < 0$ , then  $P$  is on the terminal side of  $\theta + \pi$



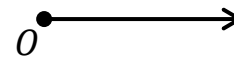
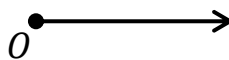
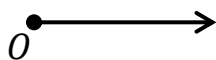
### Examples: Plotting Points in the Polar Coordinate System

Plot the points with the given polar coordinates.

1.  $P\left(2, \frac{\pi}{3}\right)$

2.  $Q\left(-1, \frac{3\pi}{4}\right)$

3.  $R(3, -45^\circ)$



### 🌀 Finding all Polar Coordinates of a Point

➤ Let  $P$  have polar coordinates  $(r, \theta)$ . Any other polar coordinate of  $P$  must be of the form...

\_\_\_\_\_

...where  $n$  is any integer.

- In particular, the pole has polar coordinates  $(0, \theta)$ , where  $\theta$  is any angle.

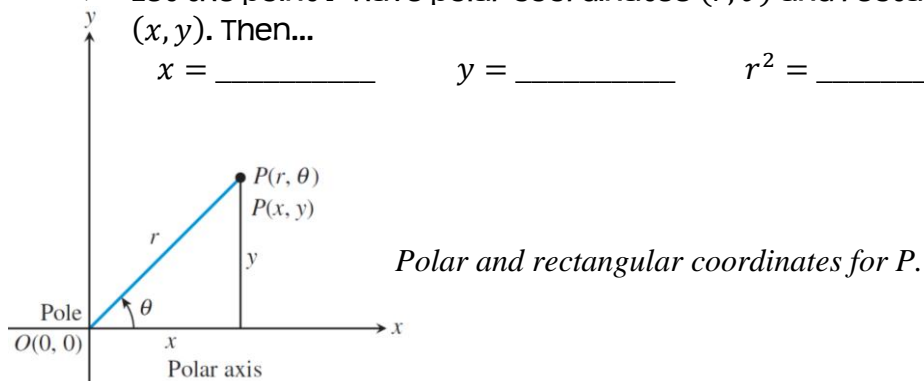
### Example 4: Finding all Polar Coordinates for a Point

If point  $P$  has polar coordinates  $(3, \pi/3)$ , find all polar coordinates for  $P$ .

## Coordinate Conversion

➤ Let the point  $P$  have polar coordinates  $(r, \theta)$  and rectangular coordinates  $(x, y)$ . Then...

$$x = \underline{\hspace{2cm}} \quad y = \underline{\hspace{2cm}} \quad r^2 = \underline{\hspace{2cm}} \quad \tan \theta = \underline{\hspace{2cm}}$$



### Examples: Converting from Polar to Rectangular Coordinates

Find the rectangular coordinates of a point with the given polar coordinates.

5.  $P\left(3, \frac{3\pi}{4}\right)$

6.  $R\left(3, -\frac{5\pi}{6}\right)$

7.  $T(2, -215^\circ)$

8.  $V(6, 80^\circ)$

When converting rectangular coordinates to polar coordinates, we must remember there are infinitely many possible polar coordinate pairs.

### Examples: Converting from Rectangular to Polar Coordinates

For the point with the given rectangular coordinates, find all polar coordinates that satisfy  $-\pi \leq \theta \leq \pi$ .

9.  $P(-3, 3)$

10.  $R(3, -5)$

11.  $T(-2, -2)$

12.  $Q(2, 5)$

Examples: Converting from Polar Form to Rectangular Form

Convert the polar equation to rectangular form.

13.  $r = 2 \cos \theta + \sin \theta$

14.  $r = -6 \sin \theta$

15.  $r \sec \theta = -12$

16.  $r = 4 \csc \theta$

Examples: Converting from Rectangular Form to Polar Form

Convert the rectangular equation to polar form.

17.  $x^2 + (y - 4)^2 = 16$

18.  $(x - 3)^2 + (y - 4)^2 = 25$

19.  $y = 3$

20.  $3y - 2x = 3$